

Stabilization of Some Linear and Nonlinear Schrödinger Equations

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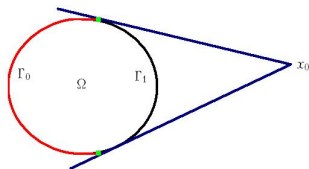
- ▶ A Quick Review of Some Introductory Results
 - ▶ Linear Schrödinger Equation with Boundary Damping [Machtyngier, ZuaZua '94]
 - ▶ Linear Schrödinger Equation with (Localized) Internal Damping [Machtyngier, ZuaZua '94]
 - ▶ Nonlinear Schrödinger Equation with Internal Damping and Homogeneous Boundary Data [M. Tsutsumi, '90]
- ▶ Nonlinear Schrödinger Equation with Internal Damping and **Inhomogeneous** Dirichlet Boundary Data [T.Ö.]
- ▶ Some Open Problems

Informal Definition of Stabilization Problem

- ▶ **Definition (Stabilization Problem):** To consider a damped problem which satisfies (desirably exponential) decay of solutions in a physically meaningful norm (e.g., L^2 , H^1) as time gets larger ($t \rightarrow \infty$).

Linear Schrödinger Equation with Boundary Damping

$$\left\{ \begin{array}{ll} iu_t + \Delta u = 0, & \text{in } \Omega \times (0, \infty), \\ \frac{\partial u}{\partial \nu} = -(m(x) \cdot \nu(x))u_t, & \text{on } \Gamma_0 \times (0, \infty), \\ u = 0, & \text{on } \Gamma_1 \times (0, \infty), \\ u(x, 0) = u^0(x) \in H_{\Gamma_1}^1, & \text{in } \Omega. \end{array} \right.$$



Linear Schrödinger Equation with Boundary Damping

- ▶ **Theorem (Well-Posedness):** There exists a unique solution u from the class $C([0, \infty); D(i\Delta)) \cap C^1([0, \infty); H_{\Gamma_1}^1)$ where $D(i\Delta) := \{u \in H_{\Gamma_1}^1 : \Delta u \in H_{\Gamma_1}^1, \frac{\partial u}{\partial \nu} = -i(m \cdot \nu)\Delta u \text{ on } \Gamma_0\}$.

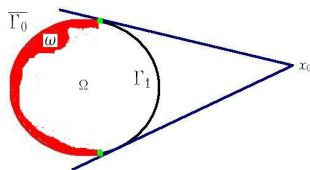
Linear Schrödinger Equation with Boundary Damping

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- ▶ **Theorem (Stabilization):** There exist positive constants C, γ such that

$$E(t) \leq CE(0)e^{-\gamma t}, \forall t \in \mathbb{R}_+$$

where $E(t) := \frac{1}{2} \|\nabla u\|_{L^2(\Omega)}^2$ is the energy function.

Linear Schrödinger Equation with (Localized) Internal Damping



$\omega \subset \Omega$ is a neighborhood of $\overline{\Gamma_0}$ in Ω and
 $a \in L^\infty(\Omega)$ such that

$$\begin{cases} a \geq 0, & \text{a.e. in } \Omega, \\ \exists a_0 > 0, & a \geq a_0 \text{ a.e. in } \omega. \end{cases}$$

Linear Schrödinger Equation with (Localized) Internal Damping

$$\begin{cases} iu_t + \Delta u + ia(x)u = 0, & \text{in } \Omega \times (0, \infty), \\ u = 0, & \text{on } \Gamma \times (0, \infty), \\ u(0) = u^0 \in L^2(\Gamma), & \text{in } \Omega. \end{cases} \quad (1)$$

► $F(t) := \frac{1}{2} \|u(t)\|_{L^2(\Omega)}^2 \Rightarrow F'(t) = - \int_{\Omega} a|u|^2 dx \leq 0.$

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- ▶ **(Theorem 2 Stabilization):** There exist positive constants C, γ such that

$$F(t) \leq CF(0)e^{-\gamma t}, \forall t \in \mathbb{R}_+.$$

Nonlinear Schrödinger Equation with Internal Damping and Homogeneous Boundary Data

$$\begin{cases} iu_t - \Delta u + g|u|^p u + iau = 0 & \text{in } \Omega \times (0, \infty), \\ u = 0 & \text{on } \Gamma \times (0, \infty), \\ u(0) = u^0 & \text{in } \Omega. \end{cases}$$

Theorem: Assume $0 < p < \infty$ if $n = 1, 2$, and $0 < p < \frac{4}{n-2}$ if $n \geq 3$,

(i) if $0 < p < 4/n$, then $\exists u \in L^\infty([0, \infty); H_0^1(\Omega))$ with $\|u\|_{H_0^1(\Omega)} \leq Ce^{-bt}$ where $b < a$ is any positive number.

(ii) if $p \geq 4/n$, then $\exists C > 0$ such that if $\|u_0\|_{H_0^1(\Omega)} \leq C$, then $\exists u \in L^\infty([0, \infty); H_0^1(\Omega))$ with $\|u\|_{H_0^1(\Omega)} \leq Ce^{-at}$.

Nonlinear Schrödinger Equation with Internal Damping and Inhomogeneous Dirichlet Boundary Data

$$\begin{cases} iu_t - \Delta u + g|u|^p u + iau = 0 & \text{in } \Omega \times (0, \infty), \\ u(0) = u^0 \in H^1(\Omega) & \text{in } \Omega, \\ u = Q & \text{on } \Gamma \times (0, \infty), \end{cases}$$

with $Q \in \{\phi : \|\phi(t)\|_b \rightarrow 0 \text{ as } t \rightarrow \infty\}$ where

$$\|\phi(t)\|_b := \sqrt{\|\phi(t)\|_{H^1(\Gamma)}^2 + \|\phi_t(t)\|_{L^2(\Gamma)}^2 + \|\phi(t)\|_{L^{p+2}(\Gamma)}^{p+2}}.$$

Theorem 1 (Existence): There exists a solution u from the class $L^\infty([0, \infty); H^1(\Omega) \cap L^{p+2}(\Omega))$.

Theorem 2 (Stabilization): $\|u(t)\|_{H^1(\Omega) \cap L^{p+2}(\Omega)} \rightarrow 0$ as $t \rightarrow \infty$

Proof of Existence

- ▶ Construct approximate equations by truncating the nonlinearity

$$f_k(|u|^2)u := \begin{cases} g|u|^p u, & |u| < k \\ gk^p u, & |u| \geq k \end{cases}$$

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- ▶ Find approximate (local) solutions by a fixed point argument.
- ▶ Use multipliers to get uniform bound on the approximate solutions and extend them to whole time interval.
- ▶ Extract a subsequence converging to the actual solution by compactness methods. ■

Proof of Stabilization

Standard multipliers, \bar{u} and \bar{u}_t give

$$\frac{d}{dt} \|u(t)\|_{L^2(\Omega)}^2 = -2a \|u(t)\|_{L^2(\Omega)}^2 + 2\text{Im} \int_{\Gamma} \bar{Q}(\nabla u \cdot \nu) d\Gamma.$$

$$\begin{aligned} & \frac{d}{dt} (\|\nabla u\|_{L^2(\Omega)}^2 + \int_{\Omega} F(|u|^2) dx) + 2a (\|\nabla u\|_{L^2(\Omega)}^2 + \int_{\Omega} F(|u|^2) dx) \\ &= 2\text{Re} \int_{\Gamma} (\bar{Q}_t + a\bar{Q})(\nabla u \cdot \nu) d\Gamma + 2a \int_{\Omega} (F(|u|^2) - f(|u|^2)|u|^2) dx. \end{aligned}$$

Continued...

In order to deal with the boundary integrals, we introduce the multiplier function

$$\rho(t) = (u, h \cdot \nabla u)_{L^2(\Omega)}$$

where h is a sufficiently smooth essentially bounded real vector field on \mathbb{R}^n with $h|_{\Gamma} = \nu$. This multiplier function has the properties $|\rho(t)| \leq C_1 E(t)$ and

$$\begin{aligned} \rho'(t) &\leq C_2 \|u(t)\|_{H^1(\Omega)}^2 - \|\nabla u \cdot \nu\|_{L^2(\Gamma)}^2 \\ &+ \|\nabla_A Q(t)\|_{L^2(\Gamma)}^2 + C_3 \|Q(t)\|_{L^2(\Gamma)} \|\nabla u \cdot \nu\|_{L^2(\Gamma)} + \|Q(t)\|_{L^2(\Gamma)} \|Q_t(t)\|_{L^2(\Gamma)} \\ &+ \int_{\Gamma} F(|Q|^2) d\Gamma + C_4 \int_{\Omega} |F(|u|^2) - f(|u|^2)| |u|^2 dx. \end{aligned}$$

Continued

We define energy and perturbed energy respectively,

$$E(t) := \|u\|_{H^1(\Omega)}^2 + \int_{\Omega} F(|u|^2) dx \xrightarrow{\text{Claim}} 0.$$

$$E_{\epsilon}(t) := E(t) + \epsilon \rho(t)$$

It is then easy to get

$$\begin{aligned} E'_{\epsilon}(t) &\leq (C_5\epsilon - 2a)E(t) - \frac{\epsilon}{4} \|\nabla u \cdot \nu\|_{L^2(\Gamma)}^2 + \left(\epsilon + \frac{C_3^2\epsilon}{2} + 8C_0^2\right) \|Q(t)\|_b^2 \\ &\leq -C_6 E(t) + C_7 \|Q(t)\|_b^2 \end{aligned}$$

Choosing ϵ enough small, we have

$$E(t) \leq E(0)e^{-C_8 t} + C_7 e^{-C_8 t} \int_0^t e^{C_8 s} \|Q(s)\|_b^2 ds \rightarrow 0$$

since $\|Q(t)\|_b \rightarrow 0$.

Rate of Dissipation

Remark (Decay Rate): The energy decays at least at the rate of Slowest(Exponential Decay Rate, Decay Rate of Q .)

Open Problems

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- ▶ Can we prove an analogous theorem with a rough boundary control? (say L^2)
- ▶ Does stabilization also hold for a (localized) internal damping?